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Propulsion Control System, AutoChief® 600

The AutoChief 600 propulsion control system is a complete control and safety systems suitable for all 2 and 4 stroke engines, both fixed and controllable pitch propellers. The system is available for single and dual propulsion lines. It features a modular design, and can easily be configured for various propulsion configurations.

AutoChief® C20

AutoChief® C20 Digital Governor Unit (DGU) Description The DGU is a diesel engine speed controller. It is used on the ship's main engine to control the engine RPM. The desired engine set-point speed is provided by either the ACP or by a manual control lever. Once the set point is established, the DGU maintains the engine RPM at all times.

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KONGSBERG July 27, 2008 32 From telegraph to bridge control system Bridge control system - Propulsion Control System. • Replaced the traditional engine telegraph, and made it possible to control the propulsion machinery directly from bridge • KONGSBERG was among the pioneers, with its AutoChief I introduced in the 1960's

Products supported A to Z

Alphabetical overview of supported Kongsberg Maritime products. ABOUT US. KONGSBERG.COM. MENU PRODUCTS. SOLUTIONS. SERVICES. ... AutoChief 4 - Propulsion control system. AutoChief 600 -

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TANKERS

4 Reliability in operation In combination, KONGSBERG tank management, automation, propulsion control and navigation subsystems enhance and improve the operation of tankers. The ultimate solution is attained when the subsystems work together in an integrated control system that includes a fully backed-up, system-wide communication network.

Kongsberg Maritime Simulator Training Courses

Maritime Simulators These courses are aimed at instructors and maintenance personnel of KONGSBERG's Maritime Training Simulators including K-Sim Navigation, Polaris, Offshore, Engine, Cargo and Dynamic Positioning.

MAN B&W

Instruction manual AutoChief® C20 INTRODUCTION This manual is generated through the configuration tool called Seamate. The manual is therefore customised for each system delivery. The intention with this manual is to explain the functionality for each major component and the total system as it's configured for each delivery.